

ATV610U75N4

variable speed drive ATV610 - 7.5 kW / 10HP -
380...415 V - IP20



Main

Range of product	Easy Altivar 610
Product or component type	Variable speed drive
Product specific application	Fan, pump, compressor, conveyor
Device short name	ATV610
Variant	Standard version
Product destination	Asynchronous motors
Mounting mode	Cabinet mount
EMC filter	Integrated conforming to EN/IEC 61800-3 category C3 with 50 m
IP degree of protection	IP20
Type of cooling	Forced convection
Supply frequency	50...60 Hz +/-5 %
Network number of phases	3 phases
[Us] rated supply voltage	380...415 V - 15...10 %
Motor power kW	7.5 kW for normal duty 5.5 kW for heavy duty
Motor power hp	10 hp for normal duty 7.5 hp for heavy duty
Line current	14.7 A at 380 V (normal duty) 13.7 A at 415 V (normal duty) 11.3 A at 380 V (heavy duty) 10.7 A at 415 V (heavy duty)
Prospective line Isc	22 kA
Apparent power	9.9 kVA at 415 V (normal duty) 7.7 kVA at 415 V (heavy duty)
Continuous output current	15.8 A at 4 kHz for normal duty 12.7 A at 4 kHz for heavy duty
Maximum transient current	17.4 A during 60 s (normal duty) 19.1 A during 60 s (heavy duty)
Asynchronous motor control profile	Constant torque standard Optimized torque mode Variable torque standard

Output frequency	0.0001...0.5 kHz
Nominal switching frequency	4 kHz
Switching frequency	2...12 kHz adjustable
Number of preset speeds	16 preset speeds
Communication port protocol	Modbus serial
Option card	Slot A: communication card, Profibus DP V1 Slot A: digital or analog I/O extension card Slot A: relay output card

Complementary

Output voltage	<= power supply voltage
Motor slip compensation	Can be suppressed Automatic whatever the load Adjustable Not available in permanent magnet motor law
Acceleration and deceleration ramps	S, U or customized Linear adjustable separately from 0.01 to 9000 s
Braking to standstill	By DC injection
Protection type	Thermal protection: motor Motor phase break: motor Thermal protection: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
Frequency resolution	Display unit: 0.1 Hz Analog input: 0.012/50 Hz
Electrical connection	Control, screw terminal: 0.5...1.5 mm ² Line side, screw terminal: 2.5...16 mm ² Motor, screw terminal: 2.5...16 mm ²
Connector type	1 RJ45 (on the remote graphic terminal) for Modbus serial
Physical interface	2-wire RS 485 for Modbus serial
Transmission frame	RTU for Modbus serial
Transmission rate	4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Type of polarization	No impedance for Modbus serial
Number of addresses	1...247 for Modbus serial
Method of access	Slave
Supply	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection
Local signalling	2 LEDslocal diagnostic: 1 LED (yellow)embedded communication status: 2 LEDs (dual colour)communication module status: 1 LED (red)presence of voltage:
Width	145 mm
Height	297 mm 350 mm with EMC plate
Depth	203 mm
Product weight	4.1 kg
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA, impedance: 250 Ohm, resolution 12 bits AI2, AI3 software-configurable temperature probe or water level sensor
Discrete input number	6

Discrete input type	DI1...DI6 programmable as logic input, 24 V DC (≤ 30 V), impedance: 3.5 kOhm DI5, DI6 programmable as pulse input: 0...30 kHz, 24 V DC (≤ 30 V)
Input compatibility	DI1...DI6: logic input level 1 PLC conforming to EN/IEC 61131-2 DI5, DI6: pulse input level 1 PLC conforming to IEC 65A-68
Discrete input logic	Positive logic (source): DI1...DI6 configurable logic input, < 5 V (state 0), > 11 V (state 1) Negative logic (sink): DI1...DI6 configurable logic input, > 16 V (state 0), < 10 V (state 1) Positive logic (source): DI5, DI6 configurable pulse input, < 0.6 V (state 0), > 2.5 V (state 1)
Analogue output number	2
Analogue output type	Software-configurable current AQ1, AQ2: 0...20 mA, resolution 10 bits Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits
Sampling duration	5 ms $\pm$ 0.1 ms (AI1, AI2, AI3) - analog input 2 ms $\pm$ 0.5 ms (DI1...DI6)configurable - discrete input 5 ms $\pm$ 1 ms (DI5, DI6)configurable - pulse input 10 ms $\pm$ 1 ms (AQ1, AQ2) - analog output
Accuracy	$\pm$ 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input $\pm$ 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: $\pm$ 0.15 % of maximum value for analog input AQ1, AQ2: $\pm$ 0.2 % for analog output
Relay output number	3
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles
Refresh time	Relay output (R1, R2, R3): 5 ms ($\pm$ 0.5 ms)
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Maximum switching current	Relay output R1, R2, R3 on resistive load, $\cos \phi = 1$: 3 A at 250 V AC Relay output R1, R2, R3 on resistive load, $\cos \phi = 1$: 3 A at 30 V DC Relay output R1, R2, R3 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 250 V AC Relay output R1, R2, R3 on inductive load, $\cos \phi = 0.4$ and $L/R = 7$ ms: 2 A at 30 V DC
Isolation	Between power and control terminals
Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth

Environment

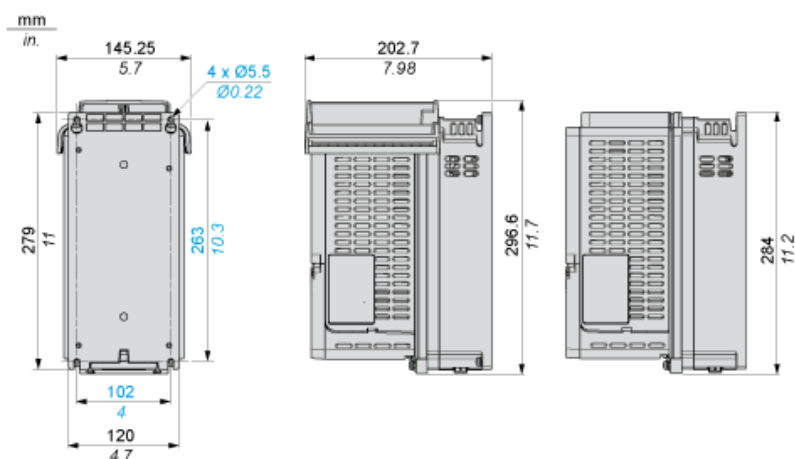
Noise level	56 dB conforming to 86/188/EEC
Power dissipation in W	216 W(forced convection) at 380 V, switching frequency 4 kHz 42 W(natural convection) at 380 V, switching frequency 4 kHz
Operating position	Vertical $\pm$ 10 degree
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 μ s - 8/20 μ s surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Pollution degree	2 conforming to EN/IEC 61800-5-1
Vibration resistance	1.5 mm peak to peak ($f = 2 \dots 13$ Hz) conforming to IEC 60068-2-6 1 gn ($f = 13 \dots 200$ Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	-15...45 °C (without) 45...60 °C (with derating factor)
Operating altitude	≤ 1000 m without 1000...4800 m with current derating 1 % per 100 m
Environmental characteristic	Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3
Standards	EN/IEC 61800-3 Environment 2 category C3 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 60721-3
Product certifications	REACH
Marking	CE

Offer Sustainability

Sustainable offer status	Green Premium product
REACH Regulation	REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
RoHS exemption information	Yes
China RoHS Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Circularity Profile	End of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

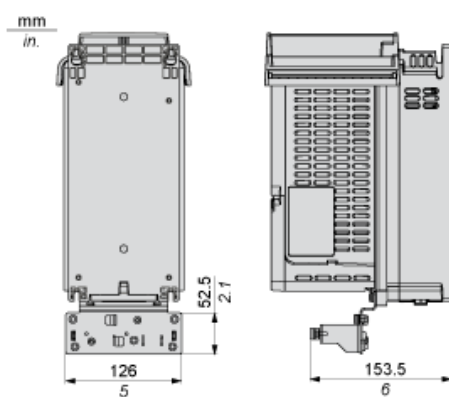
Dimensions

IP20 Drives



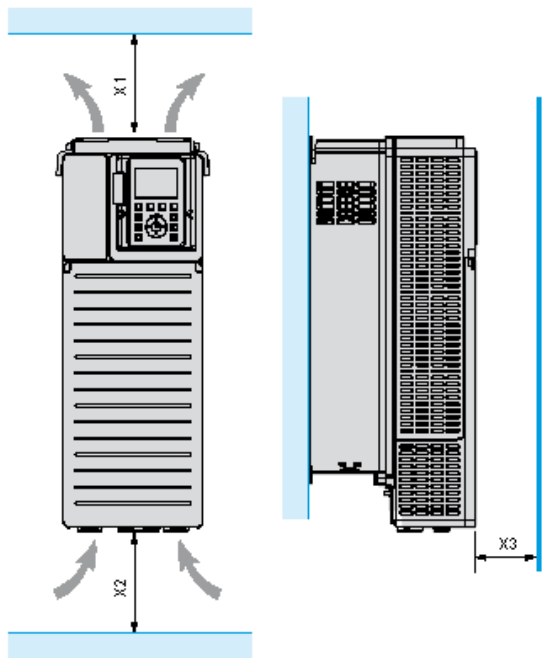
Drawings from left to right: rear view, right side view with top cover, right side view without top cover.

IP20 Drives With EMC Plate



Drawings from left to right: rear view, right side view with top cover.

Clearances

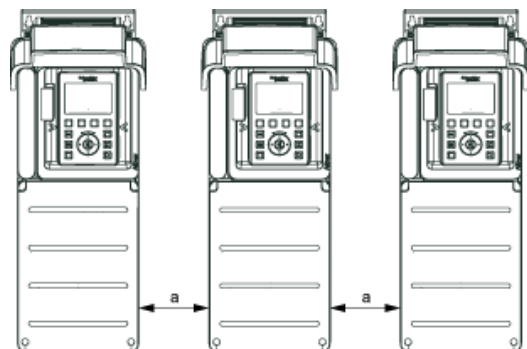


X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

- Mount the device in a vertical position ($\pm 10^\circ$). This is required for cooling the device.
- Do not mount the device close to heat sources.
- Leave sufficient free space so that the air required for cooling purposes can circulate from the bottom to the top of the drive.

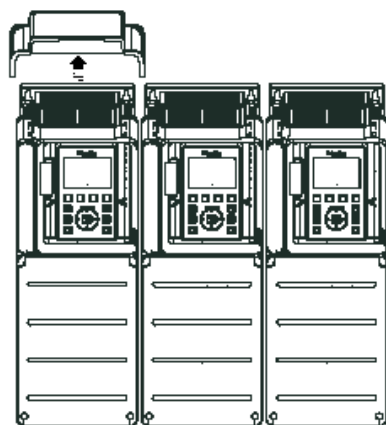
Mounting Types

Mounting Type A: Individual IP21

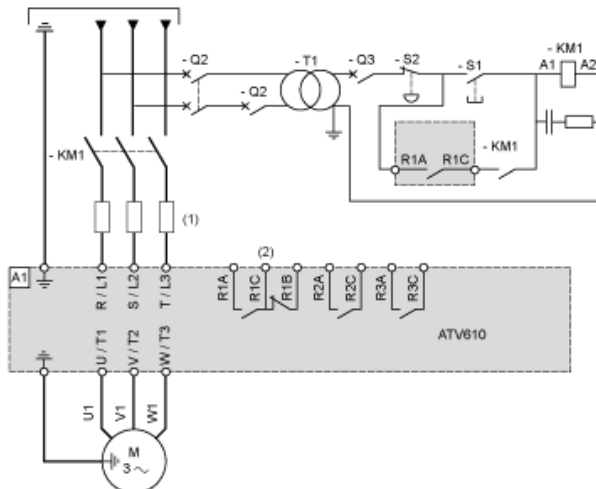


$a \geq 100 \text{ mm (3.94 in.)}$

Mounting Type B: Side by Side IP20

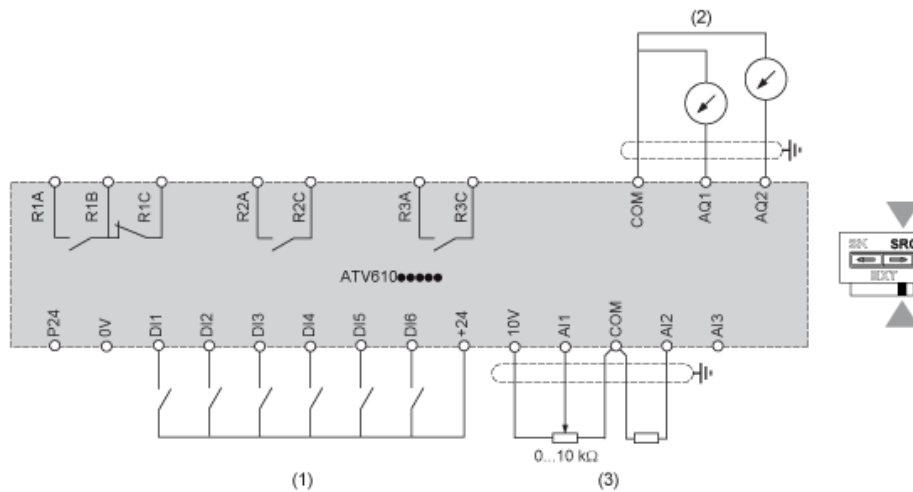


Single or Three-phase Power Supply - Diagram With Line Contactor



- (1) Line chokes
- (2) See control block wiring diagram
- A1 : Drive
- KM1 : Line Contactor
- Q2, Q3 : Circuit breakers
- S1, S2 : Pushbuttons
- T1 : Transformer for control part

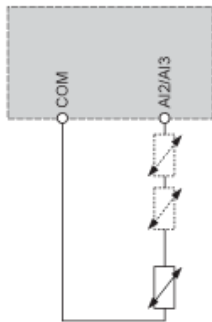
Control Block Wiring Diagram



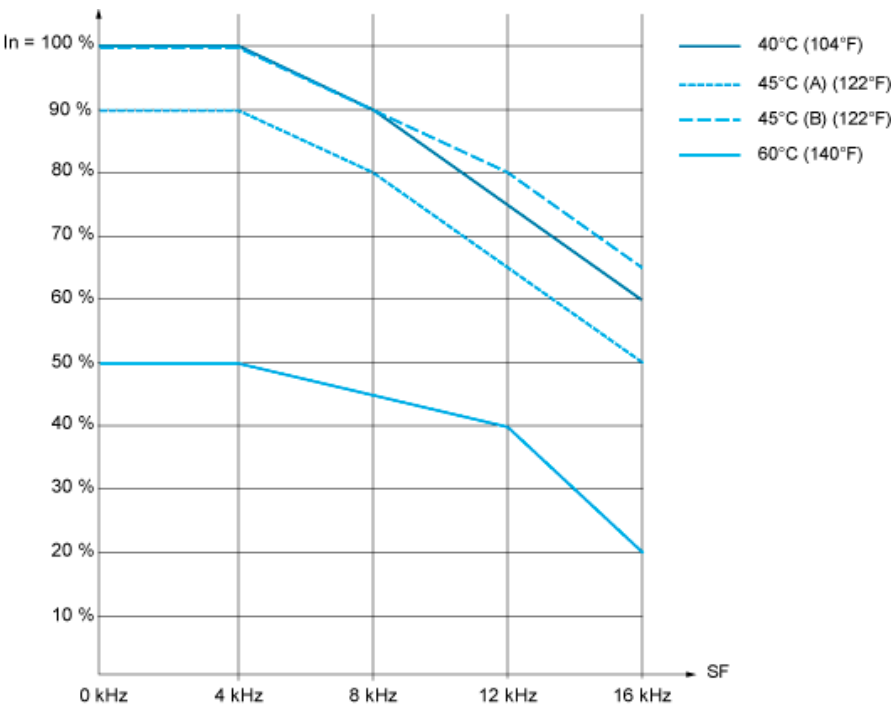
- (1) Digital Input
- (2) Analog Output
- (3) Analog Input
- R1A, R1B, R1C Relay output
- R2A, R2C Sequence relay output
- R3A, R3C Sequence relay output

Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.



Derating Curves



In : Nominal Drive Current
SF : Switching Frequency